Design of a Helicopter Deployable Ground Robotic System for Hazardous Environments

Michael S. Rose

Thesis submitted to the Faculty of the Virginia Polytechnic Institute and State University in partial fulfillment of the requirements for the degree of

Master of Science
in
Mechanical Engineering

Kevin B. Kochersberger, Chair
David C. Conner
Corina Sandu
Robert L. West, Jr.

January 25, 2010
Blacksburg, Virginia

Keywords: Robotics, Tracked Vehicle, Motion Planning, Teleoperation, Situational Awareness
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Michael Rose

From: thomas sheridan [sheridan@MIT.EDU]
Sent: Monday, January 11, 2010 9:42 AM
To: Michael Rose
Subject: Re: Use of figure

Michael,

Permission granted, not a problem, assuming you will cite the source.

Tom

On Jan 11, 2010, at 8:30 AM, Michael Rose wrote:

Dr. Sheridan –

I am writing my master’s thesis at Virginia Tech and would like permission to use a figure from your book *Telerobotics, Automation, and Human Supervisory Control*. The figure is in the introduction that demonstrates the differences between full manual control, supervisory control and full automation. If I need to contact the publisher directly for this permission, please inform.

Regards,

Michael Rose
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Michael Rose

From: David I Gertman [David.Gertman@inl.gov]
Sent: Monday, January 11, 2010 2:52 PM
To: Michael Rose
Subject: Re: Permission to cite article

Michael

Please feel free to cite the paper. Here is another link. Good luck with your thesis. Keep me posted on your progress.

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David I Gertman, PhD
Consulting Scientist
Human Factors & Instrumentation and Controls Department
Idaho National Laboratory
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HI Michael,

Feel free to use it. Good luck with your thesis!

Best wishes,

Steve

On Mon, 2010-01-11 at 07:34 -0600, Michael Rose wrote:
> Dr. LaValle -
> 
> I am working on writing my master’s thesis, and your Planning Algorithms book has been very helpful in understanding the different planning algorithms available. I am using some of the discrete domain planning algorithms in my research and am wondering if I might be able to use some figures from your books in my Thesis. I would like to use figure 2.3 from the book. May I have permission to use this figure in my thesis? If I need to contact the publisher directly for this permission, please advise.
> 
> Thanks,
> 
> Michael Rose
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